

Xsens Sirius VRU

- > Achieve new levels of accuracy with high-quality calibrated roll, pitch and unreferenced yaw data
- > Vibration- and shock- resistant signal pipeline
- > Rugged and military standard certified
- > Flexible interface and protocols for seamless integration



Description

The Xsens Sirius VRU features vibration- and shockresistant signal pipeline and offers high-quality calibrated inertial data and orientation data (roll, pitch, unreferenced yaw), even in extreme vibration conditions.

With Xsens technology inside, the all-in-one sensor system supports optimized temperature calibration, high frequency output, robustness against magnetic disturbances, and has configurable output settings for synchronization with any third-party device.

The Xsens Sirius VRU is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms.

- > White label options available
- > 3D models available on request

Sensor fusion performance

Roll, Pitch	0.2°RMS
Yaw/Heading —————	unreferenced, low
	drift
Strapdown Integration (SDI)	Yes
Gyroscope	
Standard full range	± 300 °/s
In-run bias stability	7°/h
Bandwidth (-3dB)	400 Hz

0.003 °/s/√Hz

0.08°/s/g

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g-sensitivity (calibr.)

Noise Density

Standard full range —	±8g
In-run bias stability	————— 15 μg
Bandwidth (-3dB)	470 Hz
Noise Density	

Magnetometer

Standard full range	+/-8G
Total RMS noise	1 mG
Non-linearity	0.2%
Resolution	0.25 mG

Mechanical

IP-rating ————	IP68
Operating Temperature ————————————————————————————————————	-40 to +85
Casing material	Aluminum

Mounting orientation ———	No restriction, full 360° in all axes
Dimensions	56.50 x 40.90 x 24.75 mm
Connector ————	Main: ODU (AMC HD 12 pins)
Weight ————	78.5 grams
Certifications —————	CE, FCC, RoHS, MIL-STD-202,
	ITAR free

Electrical

Input voltage ———	4.5V-24
Power consumption (typ)	<1W

Interfaces / IO

Interfaces ————	RS232, RS422, CAN
Sync Options —————	Syncin, SyncOut, ClockSync
Protocols ————	Xbus, ASCII (NMEA), CAN
Clock drift ————	10 ppm (or external)
Output Frequency ————	Up to 400Hz
Built-in-self test ————	Gyr, Acc, Mag

Software Suite

Software Suite	
GUI (Windows/Linux)	MT Manager, Firmware updater
	Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab,
	Public source code
Drivers ————	LabVIEW, ROS, GO
Support —	Online manuals, community
	and knowledge base